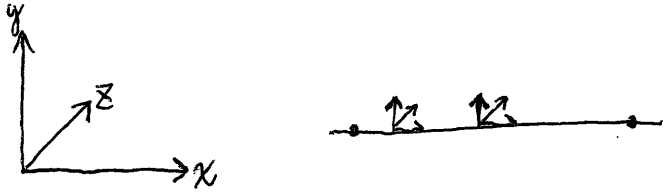
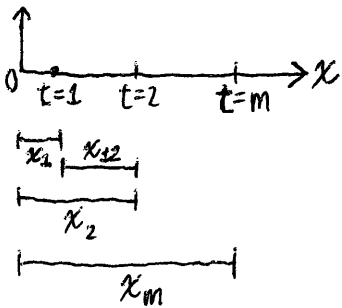


Kinematics - study of motion w/o forces involved

Kinetics - study of motion w/ forces involved



Rectilinear Motion



Velocity $V = \frac{dx}{dt}$

Speed is the scalar of the velocity

Acceleration $a = \frac{dv}{dt}$ can be >0 , $=0$, or <0

acceleration <0 is called deceleration

$$a = \frac{dv}{dx} \cdot \frac{dx}{dt} = \frac{dv}{dx} \cdot v$$

Consider the following:

-rectilinear motion

-a is constant

$$dv = a dt$$

$$\int_{V_0}^V dv = \int_{t_0}^t a dt$$

$$V = V_0 + at$$

$$V dx = a dx$$

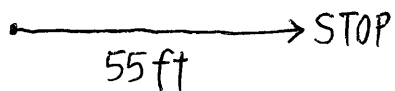
$$\int_{V_0}^V V dx = \int_{x_0}^{x_1} a dx$$

$$\frac{1}{2}(V^2 - V_0^2) = a(x - x_0)$$

$$V = at + V_0$$

$$x = \frac{1}{2}at^2 + V_0t + x_0$$

Ex. $V=30 \text{ mi/h}$, $t=0$, $d=16 \text{ ft/s}^2$ or $a=-16 \text{ ft/s}^2$



Find:

- * Can the vehicle stop legally?
- * $a \rightarrow t$
- * $V \rightarrow t$
- * $V \rightarrow x$

$$V=30 \text{ mi/h} = 44 \text{ ft/s}$$

$$a=-16 \text{ ft/s}^2$$

$$V=V_0+at$$

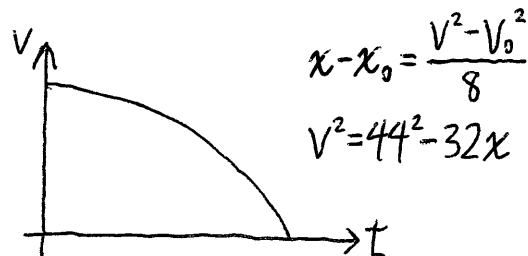
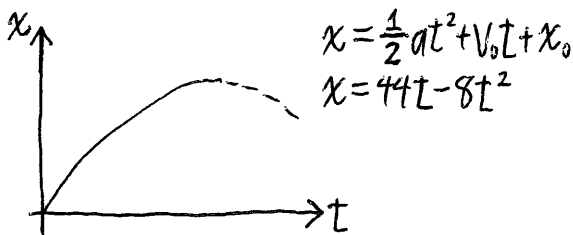
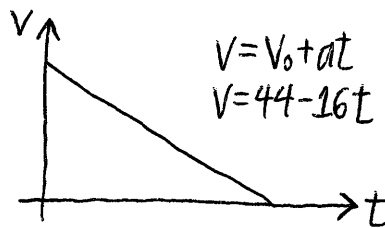
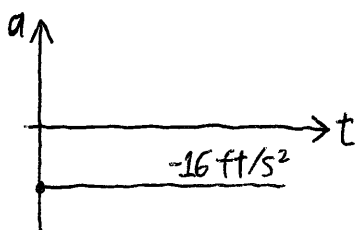
$$0=44-16t \Rightarrow t=2.75 \text{ s}$$

$$x-x_0 = \frac{V^2-V_0^2}{2a}$$

$$x = \frac{-44^2}{-2 \times 16} = 60.5 \text{ ft} > 55 \text{ ft} \quad \text{Cannot stop legally}$$

$$x = \frac{1}{2}at^2 + V_0t + x_0$$

$$x = \frac{1}{2}(-16)(2.75)^2 + 44(2.75) + 0 = -60.5 + 121 = 60.5 \text{ ft}$$

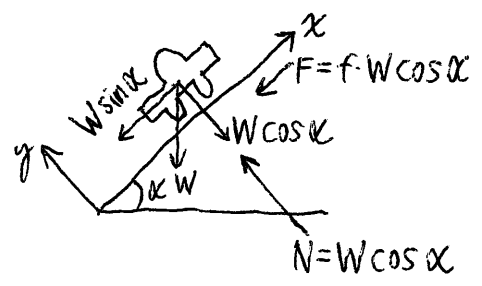
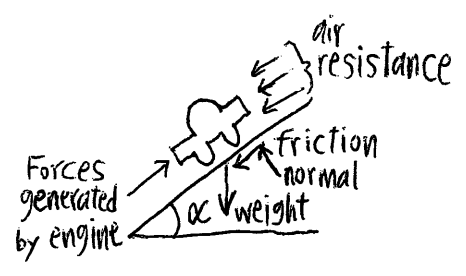


$$V = at + V_0$$

$$x - x_0 = \frac{V^2 - V_0^2}{2a}$$

$$x = \frac{1}{2}at^2 + V_0t + x_0$$

2.2.2 Breaking Distance



$f = 0.6$ dry pavement
 $f = 0.3$ wet "

$$D_b = x \cdot \cos \alpha \quad \alpha = 0, x = D_b$$

$$\Sigma F_x = 0: N = W \cos \alpha$$

$$\Sigma F_y = 0: \frac{W}{g} \cdot a + W \cdot f \cos \alpha + W \sin \alpha = 0 \Rightarrow \frac{V^2 - V_0^2}{2gD_b} \cdot \frac{\cos \alpha}{\cos \alpha} + f \frac{\cos \alpha}{\cos \alpha} + \frac{\sin \alpha}{\cos \alpha} = 0$$

$$x - x_0 = \frac{V^2 - V_0^2}{2a} \Rightarrow \frac{D_b}{\cos \alpha} = \frac{V^2 - V_0^2}{2a}$$

$$\frac{V_0^2 - V^2}{2gD_b} = -f - \tan \alpha$$

$$\frac{V^2 - V_0^2}{2gD_b} \cos \alpha + f \cos \alpha + \sin \alpha = 0$$

$$D_b = \frac{V^2 - V_0^2}{2g(f \pm G)} \quad \text{where } G = \tan \alpha$$

Ex 2 in Ch 2

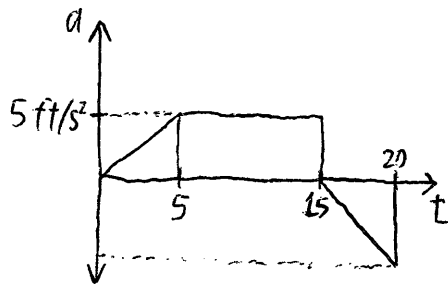
$$\tan \alpha = a = 2\% \quad \alpha = 1.15^\circ$$

$$d = 8 \text{ ft/s}^2 \quad D_b = x \cos \alpha \approx x$$

$$x = \frac{V^2 - V_0^2}{2a} = \frac{V^2 - V_0^2}{2(8)} = \frac{V^2 - V_0^2}{2g(f+a)} \Rightarrow 2(8) = 2g(f+0.02)$$

$$f = 0.23$$

Ex 1 in Ch 2



Find:

* $V \rightarrow t$

* $D(20)$

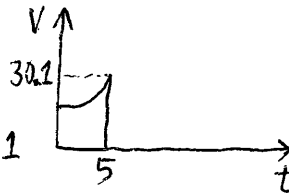
$$V(0) = 12 \text{ mi/h} = 17.6 \text{ ft/s}$$

I) $0 \leq t \leq 5 \text{ min}$

$$\frac{dv}{dt} = a = t$$

$$V = \frac{t^2}{2} + V_0$$

$$V = \frac{t^2}{2} + 17.6 = 30.1$$



$$\frac{dx}{dt} = V$$

$$x = \frac{t^3}{6} + 17.6t + x_0$$

$$x = \frac{5^3}{6} + 17.6(5) = 108.8 \text{ ft}$$

II) $5 \leq t \leq 15$

$$0 \leq (t-5) \leq 10$$

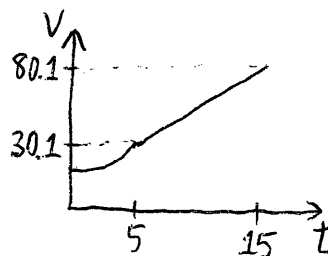
$$\frac{dv}{dt} = a = 5$$

$$V = 5(t-5) + V_0$$

$$V = 5(10) + 30.1 = 80.1$$

$$x = \frac{5(t-5)^2}{2} + 30.1(t-5) + x_0 \quad x_0 = 108.8 \text{ ft}$$

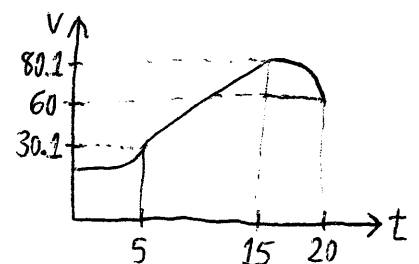
$$x = 659.8 \text{ ft}$$

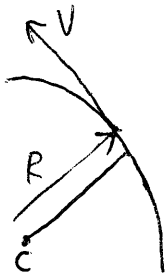
III) $0 \leq (t-15) \leq 5$

$$\frac{dv}{dt} = \frac{-8}{5}(t-15)$$

$$V = \frac{-8}{5} \cdot \frac{(t-15)^2}{2} + 80.1$$

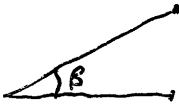
$$x = \frac{-8}{5} \cdot \frac{(t-15)^3}{6} + 80.1(t-15) + 659.8$$



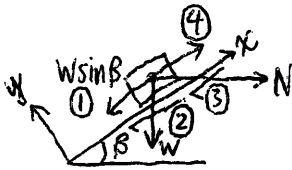


$$a_t = \frac{dv}{dt} \quad a_n = \frac{V^2}{R}$$

$$\Sigma F_t = m \frac{dv}{dt} \quad \Sigma F_n = m \frac{V^2}{R}$$



$e = \tan \beta$
 ↓
 rate of superelevation



$$\Sigma F_y = W \cos \beta + m a_n \cdot \sin \beta = 0$$

$$\Sigma F_x = W \sin \beta + f_s \cdot W \cos \beta + f_s \cdot \frac{W}{g} \cdot \frac{V^2}{R} \cdot \sin \beta = \frac{W}{g} \frac{V^2}{R} \cos \beta$$

①
②
③
④

$$\tan \beta + f_s + \frac{f_s V^2}{gR} \cdot \tan \beta = \frac{V^2}{gR}$$

$$e + f_s + f_s \frac{V^2}{gR} \cdot e = \frac{V^2}{gR} \quad e + f_s = \frac{V^2}{gR} (1 - e f_s)$$

Ex. $W = 2000 \text{ lb}$ $v = 88 \text{ ft/s}$ $F = ?$
 $R = 500 \text{ ft}$ $d = 8 \text{ ft/s}^2 = a_t$

$$F_t = m \cdot a_t = \frac{2000}{g} (-8) = -497 \text{ lb}$$

$$F_n = m \cdot a_n = m \cdot \frac{V^2}{R} = \frac{2000}{32.2} \left(\frac{88^2}{500} \right) = 962 \text{ lb}$$

$$F = \sqrt{F_t^2 + F_n^2} = 1083 \text{ lb}$$

Ex. $R = 1000 \text{ ft}$ $f = 0.2$
 $V = 60 \text{ mi/h}$ $\beta = ?$
 $= 88 \text{ ft/s}$

$$\tan \beta = e \quad e = \frac{V^2}{gR} - f_s = \frac{(88)^2}{32.2 \cdot 1000} - 0.2 = 0.04$$

$$\tan \beta = 0.04 \quad \beta = 2.3^\circ$$

$e = 0$, Max $V = ?$

$$V = \sqrt{f_s \cdot gR} = \sqrt{0.2 \times 32.2 \times 1000} = 80 \text{ ft/s} \cong 55 \text{ mi/h}$$

HW 1: 2.6, 2.8, 2.11 due 9/22/08

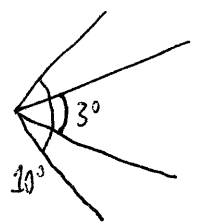
20/20: normal vision

$$H = \frac{1}{3} \text{ in} \quad d = 20 \text{ ft}$$

20/40

$$H = \frac{1}{3} \text{ in} \quad d = 10 \text{ ft}$$

Vision Region(s)



Ex. 20/20 vision $H = 2 \text{ in}$ $d = 90 \text{ ft}$
 20/50 vision $H = 2 \text{ in}$ $d = ?$

$$x = 90 \text{ ft} \cdot \frac{20}{50} = 36 \text{ ft}$$

20/60 vision $H = ?$ $d = 90 \text{ ft}$

$$H = 2 \text{ in} \cdot \frac{60}{20} = 6 \text{ in}$$

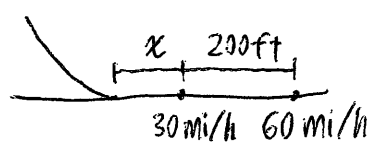
$$90 : 6 = 36 : x \quad \text{Find } H$$

$$x = \frac{36 \cdot 6}{90} = 2.4 \text{ in}$$

20/40 vision

$d = 50 \text{ ft}$ $H = 1 \text{ in}$
 for 20/20

$V_0 = 60 \text{ mi/h}$ $V = 30 \text{ mi/h}$
 $H = 8 \text{ in}$



$$d = 8 \times 50 = 400 \text{ ft (for 20/20)}$$

$$d = 200 \text{ ft (for 20/40)}$$

$$V_0 = 88 \text{ ft/s} \quad V = 44 \text{ ft/s}$$

$\delta =$ perception
 reaction time

$$x = \frac{V_0^2 - V^2}{2g(f+G)} + V_0 \cdot \delta = 433 \text{ ft}$$

\downarrow \swarrow
 88 ft/s 1.5

2 ways to classify highways:

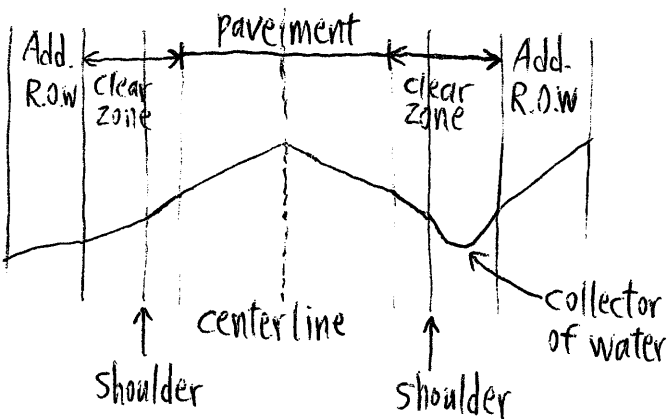
1) functionality

2) entity

	Rural	Urban
Principal Arterials	Freeways Others	Interstate Freeways Freeways Others
Minor Arterials (Collectors)	Major Minor Local Roads	Collectors Local Streets

{ cross-section
horizontal alignment
superelevation
vertical alignment
intersections

Cross-Section

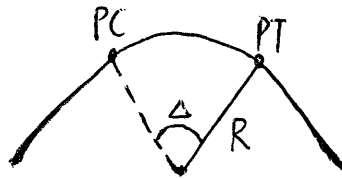


slope = Normal crown
 $\frac{1}{8}$ to $\frac{1}{4}$ in/ft

9/17/08

HW 1 postponed → due Fri 9/26

Horizontal Alignment



A is located:
 14 sta from a ref. point
 1400 ft
 1 sta = 100 ft

$$L = 2\pi R \cdot \frac{\Delta}{360}$$



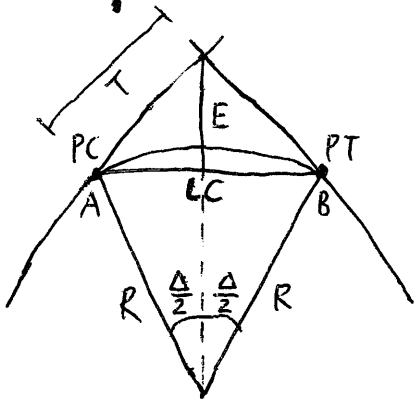
Arc definition

$$\frac{100}{2\pi R} = \frac{D}{360} \Rightarrow D = \frac{5729.58^\circ}{R}$$



Chord definition

$$\sin\left(\frac{D}{L}\right) = \frac{50}{R}$$



M = middle ordinate distance

$$M = R - R \cos \frac{\Delta}{2} = R(1 - \cos \frac{\Delta}{2})$$

T = length of tangent L = length of curvature

$$T = R \tan \frac{\Delta}{2}$$

$$L = 100 \cdot \frac{\Delta}{D}$$

LC = long chord

$$LC = 2R \sin \frac{\Delta}{2}$$

$$e + f_s = \frac{V^2}{gR} \quad \text{OR} \quad e + f_s = \frac{V^2}{15R}$$

$$e = 0.12 \text{ ft/ft}$$

$$\begin{array}{l} \searrow 0.1 \\ \searrow 0.08 \end{array}$$

max e

$$f_s = 0.17 \quad 20 \text{ mi/h}$$

$$0.10 \quad 70 \text{ mi/h}$$

max f_s

$$R_{\min} = \frac{V^2}{g(e_{\max} + f_s)}$$

$$R > R_{\min}$$

Ex. Calculate D & R_{\min}

$$\Delta = 100^\circ$$

$$V = 50 \text{ mi/h}$$

$$f_{\max} = 0.14$$

$$R_{\min} = \frac{V^2}{15(e_{\max} + f_s)} = \frac{50^2}{15(0.1 + 0.14)} = 695 \text{ ft}$$

$$D = \frac{5729.58^\circ}{R} = 8.24^\circ$$

Ex. Calculate e

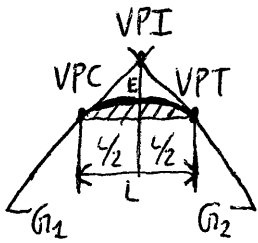
$$R = 800 \text{ ft}$$

$$V = 50 \text{ mi/h}$$

$$f_s = 0.14$$

$$e = \frac{V^2}{15R} - f_s = \frac{50^2}{15(800)} - 0.14 = 0.07 \text{ ft/ft}$$

Vertical Alignment



freeways 2%-6%
local streets 6%
railroad max 4%

percent grade $A = G_2 - G_1$ < 0 crest curve
 > 0 sag curve

Absolute value of change in grade $k = \frac{L}{|A|}$

$E = \frac{A \cdot L}{800}$ External Distance

offset $\Rightarrow y = 4E \left(\frac{x}{L}\right)^2$

Highest point $X = \frac{L G_1}{G_1 - G_2}$

Elevation of P = Elevation of VPC + $\frac{G_1 x}{100}$ + y

Ex. $L = 600$ ft

$G_1 = 4\%$ $G_2 = -2\%$

25+60.55 sta. \leq VPI (x)

VPC = ?

Middle of the curve

Curve elevation at 24 and 27 sta.

VPI elev. 648.64 ft

	Pt. Sta	x	tan elev.	off-set	curve elev.
VPC	22+60.55	0	636.64	0	636.64
	24	139.45	642.21	-0.97	641.25
VPI	25+60.55	300	648.64	-4.5	644.14
	27			-9.66	644.56
VPT				-18	642.64
High	26+60.55	400	652.64	-8.0	644.64

$A = G_2 - G_1 = -2 - (4) = -6\%$

$k = \frac{L}{|A|} = \frac{600}{6} = 100$ ft

$E = \frac{AL}{800} = \frac{-6 \times 600}{800} = -4.5$ ft

$X = \frac{L G_1}{G_1 - G_2} = \frac{600 \times 4}{4 + 2} = 400$ ft

$y = 4E \left(\frac{x}{L}\right)^2 = 4(-4.5) \left(\frac{400}{600}\right)^2 = -8.0$

Tan elev. VPC: $648.64 - 300(.04) = 636.64$

Tan elev. P: $636.64 + 400(.04) = 652.64$

x for 24 Sta: $2400 - 2260.55 = 139.45$

Tan elev. 24 Sta: $636.64 + 139.45 \times .04$

y (24 Sta) = $4(-4.5) \left(\frac{139.45}{600}\right)^2$

9/24/08

Exercise 2.20

$L = 2000 \text{ ft}$

$G_1 = 3\% \quad G_2 = -5\%$

VPI intersects at 52+60.55 sta

VPI elevation = 877.62 ft

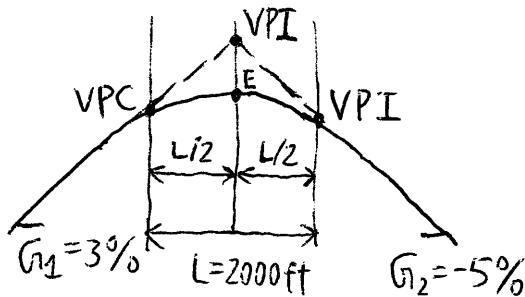
Find:

* VPC

* VPT

* high point

* 54.00 sta



$A = G_2 - G_1 = -5 - 3 = -8\%$

$K = \frac{L}{|A|} = \frac{2000}{8} = 250 \text{ ft}/\%$

$E = \frac{AL}{800} = \frac{-8 \times 2000}{800} = -20 \text{ ft}$

	Point	x	Tangent elevation	y	Curve elevation y'
	VPC	42+60.55	0	847.62	847.62
high pt.		50+10.55	750	870.12	-11.25
	VPI	52+60.55	1000	877.62	-20
54.00		54.00	1139	881.79	-25.95
	VPT	62+60.55	2000	907.62	-80

Note:

$y' = T_E - y$

$T_{E(VPC)} = \frac{L}{2} \times G_1 = 1000 \times 3\% = 30 \text{ ft}$

$y_{(VPT)} = 4E \left(\frac{x}{L}\right)^2 = 4 \times (-20) \left(\frac{2000}{2000}\right)^2 = -80 \text{ ft}$

High Point $\rightarrow x = \frac{L G_1}{G_2 - G_1}$

$x = \frac{2000 \times 3}{8} = 750 \text{ ft}$

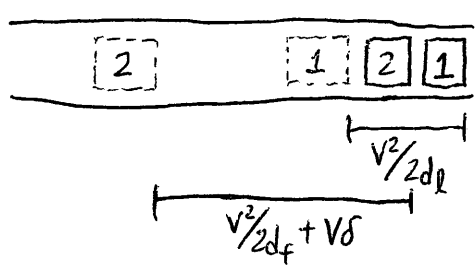
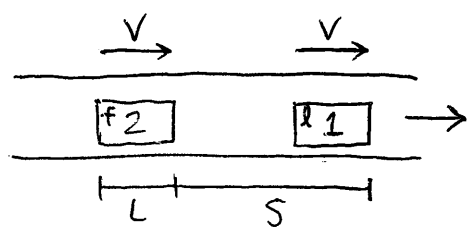
$T_{E(54.00)} = 1139 \times 3\% = 847.62$

$y = 4(-20) \left(\frac{1139}{2000}\right)^2 = -25.95$

$T_{E(HP)} = x \times G_1 = 750 \times 3\% = 12.5 \text{ ft}$

$y_{(HP)} = 4E \left(\frac{x}{L}\right)^2 = 4 \times (-20) \left(\frac{750}{2000}\right)^2 = -11.25 \text{ ft}$

Uninterrupted



V_0 = initial speed of vehicle
 d_l = deceleration rate of leading vehicle
 d_f = deceleration rate of following vehicle
 δ = perception-reaction time
 x_0 = safety margin after stop
 L = length of the vehicle
 N = number of vehicles in train

$$x_l = \frac{V^2}{2d_l} \quad x_f = \frac{V^2}{2d_f} + V\delta$$

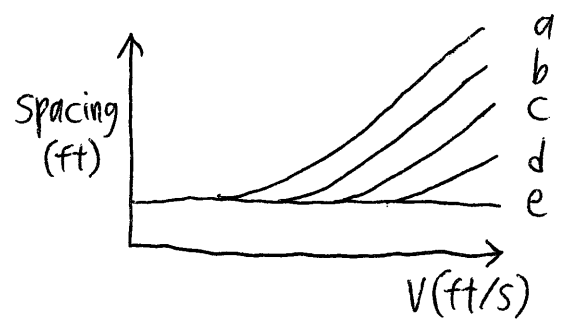
$$S = x_f - x_l + NL + x_0$$

$$x_f = S + x_l - NL - x_0$$

$$S = V\delta + \frac{V^2}{2d_f} - \frac{V^2}{2d_l} + NL + x_0$$

d_n = normal deceleration rate
 d_e = emergency " "
 ∞ = instantaneous stop

- a best safety cond.
- b
- c
- d
- e worst safety cond.



$L = 20 \text{ ft}$
 $N = 1$
 $x_0 = 3 \text{ ft}$
 $\delta = 1 \text{ s}$
 $d_n = 8 \text{ ft/s}^2$
 $d_e = 24 \text{ ft/s}^2$

Regime	Decel. leading veh.	Decel. following veh.
a	∞	d_n
b	d_e	d_n
c	∞	d_e
d	d_e	d_f
e	no breaking	no breaking

Ex. (Prob 3.1)

$N=1$

b safety regime

$\delta = 1.5 \text{ s}$

$d_n = 8 \text{ ft/s}^2$

$d_e = 32 \text{ ft/s}^2$

$L = 40 \text{ ft}$

$x_0 = 4 \text{ ft}$

Find:

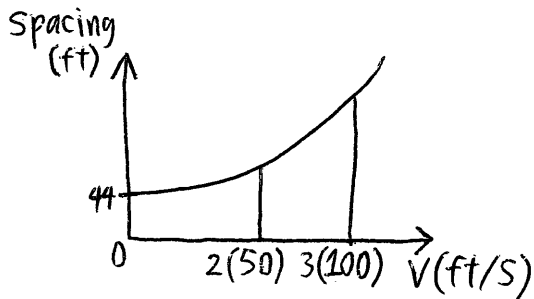
$* S \leftrightarrow V$

$d_x = d_e$

$d_f = d_n$

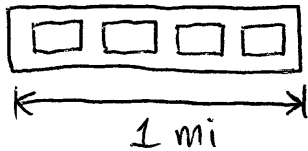
$$S = V \cdot \delta + \frac{V^2}{2d_n} - \frac{V^2}{2d_e} + NL + x_0$$

① $S = V(1.5) + \frac{V^2}{2(8)} - \frac{V^2}{2(32)} + 1(40) + 4$

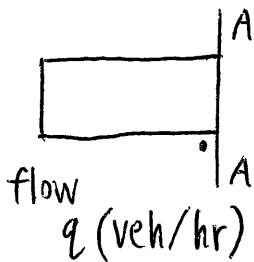


② $S = 50(1.5) + \frac{50^2}{16} - \frac{50^2}{64} + 44$

Concentration (K): number of vehicles per roadway length



$K = \frac{4 \text{ veh.}}{1 \text{ mi}} = 4 \text{ veh./mi}$ $S = 1/K$



$h = \frac{1}{q}$ headway

Average Speed

Time Mean Speed

$M_t = \frac{1}{N} \sum_{i=1}^N v_i$

Space Mean Speed

$t_i = D/v_i$

$t_{avg} = \frac{1}{N} \sum_{i=1}^N \frac{D}{v_i}$

$M_s = \frac{1}{\frac{1}{N} \sum_{i=1}^N \frac{1}{v_i}}$

HW 2 due 10/8

2.21, 3.9, 3.14, 3.17
?

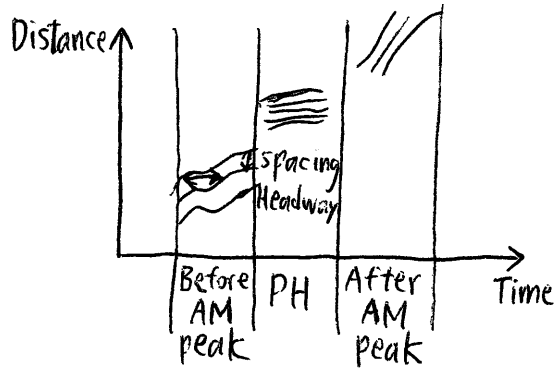
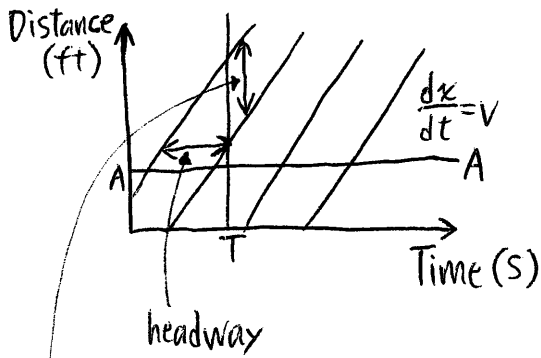
Ex.

30, 40, 50, 60 ft/s

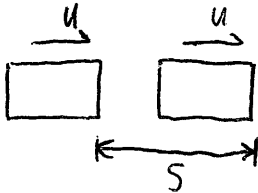
$$M_t = \frac{1}{4} \left(\frac{30+40+50+60}{1} \right) = 45 \text{ ft/s}$$

$$M_s = \frac{1}{\frac{1}{4} \cdot \left(\frac{1}{30} + \frac{1}{40} + \frac{1}{50} + \frac{1}{60} \right)} = 42.1 \text{ ft/s}$$

$M_t \neq M_s$ are different



spacing

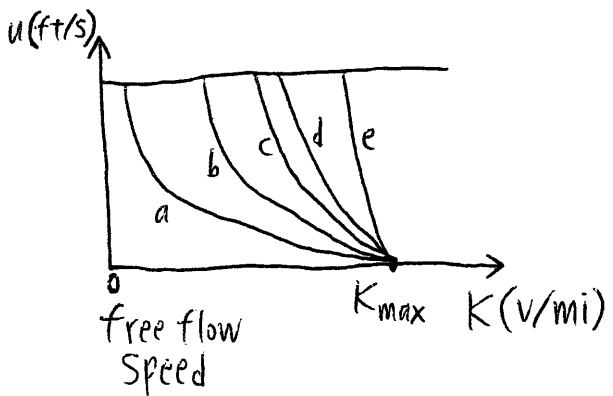


$$h = \frac{S}{u} \quad h = \frac{1}{q} \quad K = \frac{1}{S} \Rightarrow S = \frac{1}{K}$$

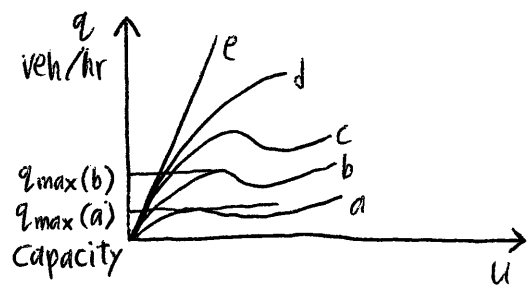
$$\frac{1}{q} = \frac{1}{K \cdot u} \quad q = K \cdot u$$

$$S = u\delta + \frac{u^2}{2d_f} - \frac{u^2}{2d_g} + NL + x_0$$

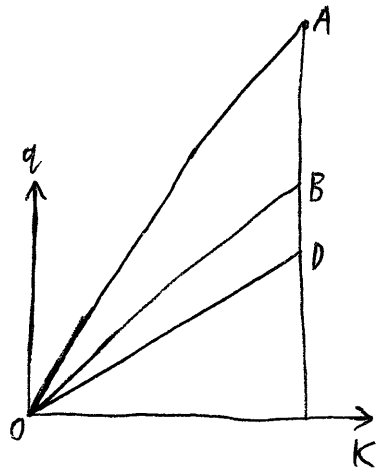
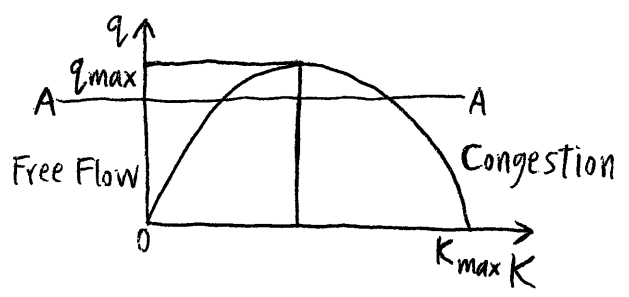
$$K = \frac{1}{S} = \frac{1}{u\delta + \frac{u^2}{2d_f} - \frac{u^2}{2d_g} + NL + x_0}$$

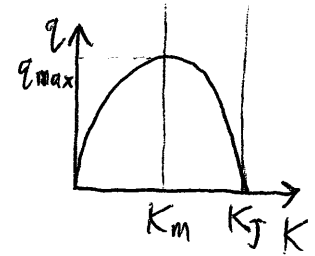
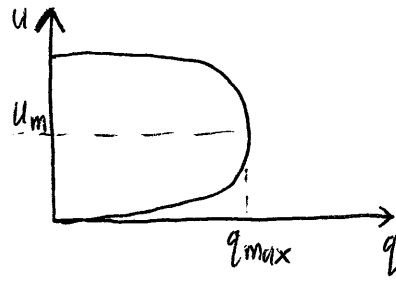
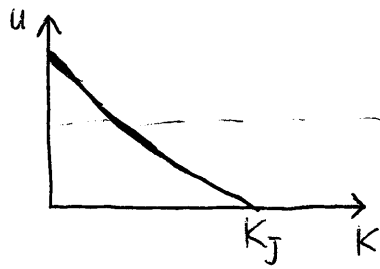


$$q = Ku = \frac{u}{u\delta + \frac{u^2}{2d_f} - \frac{u^2}{2d_e} + NL + X_0}$$



$$q = Ku \Rightarrow q = K \cdot u(K)$$



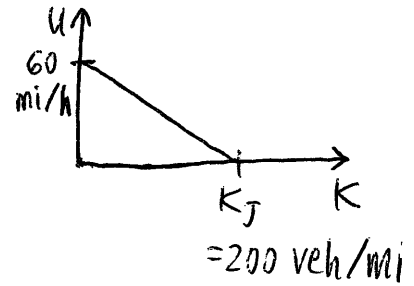


Ex. Exercise 3.4

$$S = \frac{0.30}{(60-u)}$$

- Find
- * $u-K$
 - * $u-q$
 - * $q-K$
 - * q_{max}

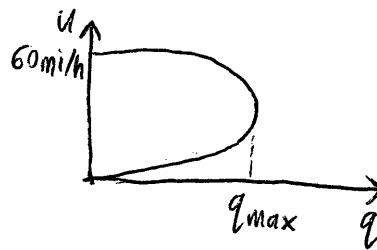
$$\frac{1}{K} = \frac{0.30}{60-u} \Rightarrow K = \frac{60-u}{0.30} = 200 - 3.33u$$



$$u = \frac{q}{K} = \frac{q}{60-u} \cdot 0.30$$

$$0.30q = 60u - u^2$$

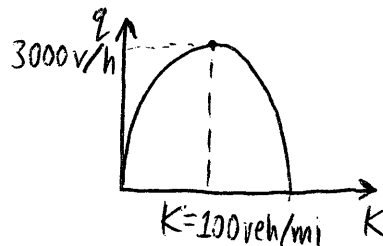
$$q = \frac{60u - u^2}{0.30} = 200u - 3.33u^2$$



$$K = 200 - 3.33 \frac{q}{K}$$

$$K^2 = 200K - 3.33q$$

$$q = \frac{200K - K^2}{3.33} = 60K - 0.3K^2$$

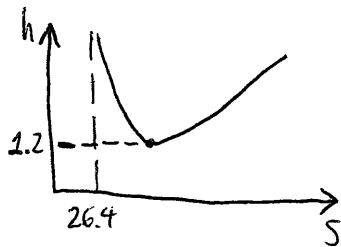


$$q_{max} \Rightarrow \frac{dq}{dK} = 0 \quad 60 - 0.6K = 0$$

$$K = 100$$

$$q_{max} = 6000 - 3000 = 3000 \text{ veh/hr}$$

Ex.



jam conditions $u=0$ $K = \frac{60}{0.3}$



$$S = \frac{1}{K} = \frac{0.3}{60} = 0.005 \text{ mi} = 26.4 \text{ ft}$$

at capacity

$$h = \frac{1}{q_{\max}} = \frac{3600}{3000} = 1.2$$

Ex. Exercise 3.8

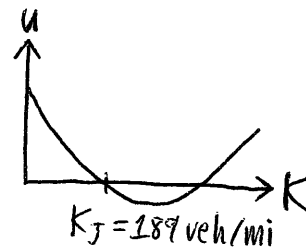
$$u + 2.6 = 0.001(K - 240)^2$$

Find: u_{ff} , K_J , q_{\max} , u_m
 ↑
 speed of free flow

$$K=0 \Rightarrow u_{ff} = 0.001(240)^2 - 2.6 = 55 \text{ mi/h}$$

$$u=0 \Rightarrow (K-240)^2 = 2.6$$

$$K_J = 189 \text{ or } 291 \text{ veh/mi}$$



$$\frac{dq}{dK} = 0 \quad q = u \cdot K = (0.001(K-240)^2 - 2.6)K$$

$$= 0.001K^3 - 0.48K^2 + 55K$$

$$\frac{dq}{dK} = 0.003K^2 - 0.96K + 55 = 0 \quad K = 75 \text{ or } 245$$

~~km~~ $K_m = 75$ $q_{\max} = 1846 \text{ veh/hr}$

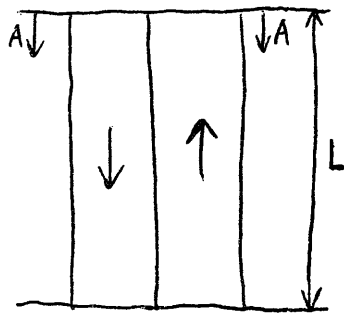
$$u_m = \frac{q_{\max}}{K_m} = \frac{1846}{75} = 24.6 \text{ mi/h}$$

For Exam 1:

- ① Rectilinear and Curvilinear Motion
- ② Perception Reaction Time & Visual Acuity
- ③ Horizontal & Vertical Alignment
- ④ $u-K-q$
- ⑤ The moving observer
- ⑥ Shock Waves

The moving observer method

$$q = u \cdot K$$



1st case

$$q = \frac{N_o}{T}$$

2nd case

$$K = \frac{N_p}{L}$$

$$N_p = KL = KVT$$

$$= K \times L = K \times V \times T$$

3rd case

M_o : number of vehicles overtake by the observer

M_p : number of vehicles overtaken the observer

$$M = M_o - M_p$$

$$= qT - KVT$$

$$\frac{M}{T} = q - KV$$

↓ T_a M_a

↑ T_w M_w

$$q = \frac{M_w + M_a}{T_w + T_a}$$

* M_o : car faster than obs.

* M_p : car slower than obs.

Ex. $L = 5$ mi

↑ w	V	$M_o - M_p$
1	10	100
2	20	-150

Find:

* q

* K

* u_s

* S

* h

$$\frac{M_1}{T_1} = q - KV_1$$

$$\frac{100}{T_1} = q - 10K$$

$$\frac{100}{0.5} = q - 10K \quad \frac{-150}{0.25} = q - 20K$$

$$200 = q - 10K \quad -600 = q - 20K$$

$$-600 = 200 + 10K - 20K$$

$$K = 80 \text{ veh/mi}$$

$$200 = q - 800$$

$$q = 1000 \text{ veh/hr}$$

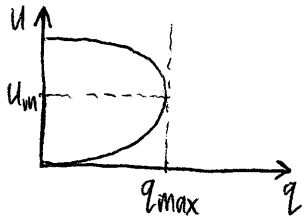
$$h = \frac{1}{q} = \frac{1}{1000} = 0.001 \text{ hr} = 3.6 \text{ s}$$

$$S = \frac{1}{K} = \frac{1}{80} = 0.0125 \text{ mi} = 66 \text{ ft}$$

$$u = \frac{q}{K} = \frac{1000}{80} = 12.5 \text{ mi/hr}$$

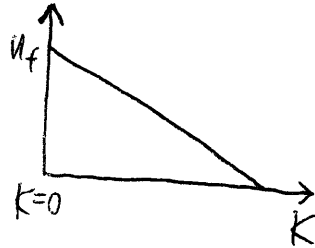
$$q = q(u) \quad q = a + bu$$

$$q_{\max} \text{ \& } u_m, \quad K_m = \frac{q_{\max}}{u_m}$$



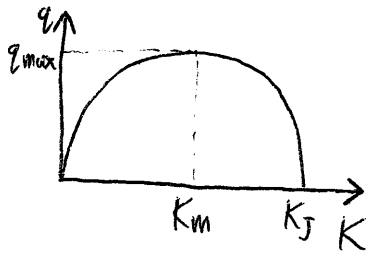
$$\frac{dq}{du} = 0 \rightarrow u$$

$$u_{ff} \quad K=0 \quad u = u(K)$$



To get q_{\max} ,
need $q-u$ or $q-K$

$$K_J \quad q=0 \quad q = q(K)$$



$q_{\max}?$

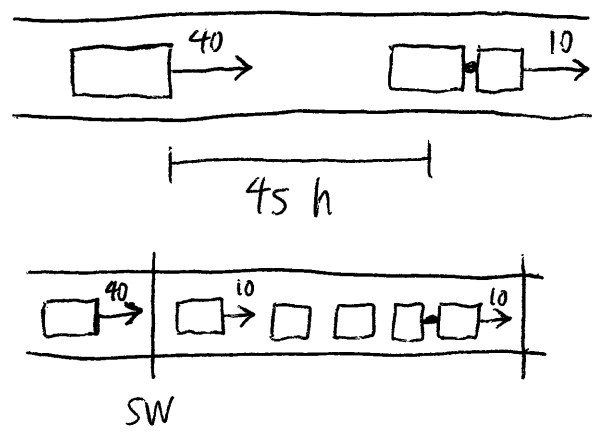
$$\frac{dq}{dK} = 0 \rightarrow K_m \rightarrow q_{\max}$$

$$q=0 \rightarrow K_J$$

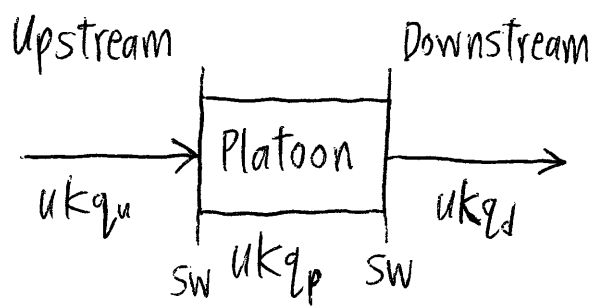
$$u_m = \frac{q_{\max}}{K_m}$$

10/6/08

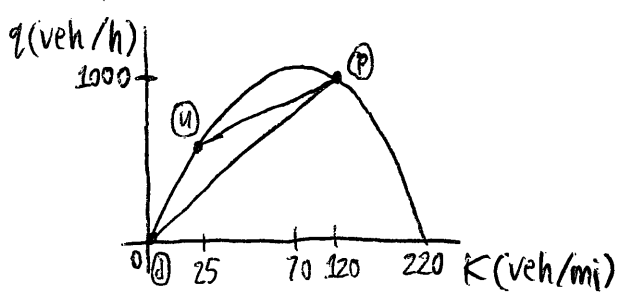
Shockwaves



- (a) normal flow
- (b) truck enters
- (c) platoon begins
- (d)
↔ ↔
- (e)
→ ←
- (f) truck exits
- (g) →
- (h)

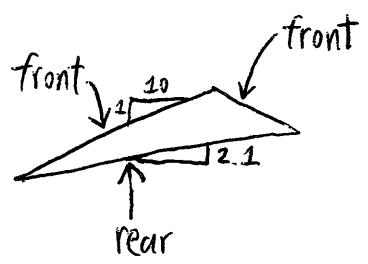
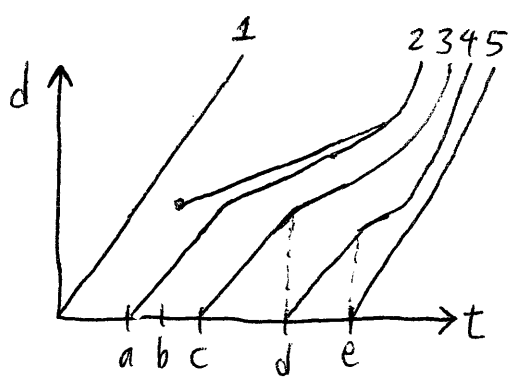


Graphical



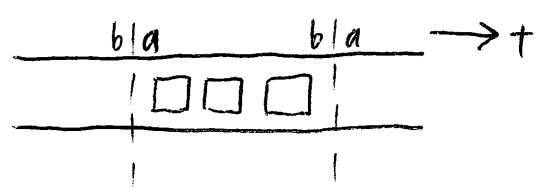
$$\frac{\Delta q}{\Delta K} = \frac{1200 - 1000}{120 - 25} = 2.1 \text{ mi/h}$$

- $u_{up} = 40 \text{ mi/h}$
- $q_{up} = 1000 \text{ veh/h}$
- $K_{up} = 25 \text{ veh/mi}$
- $u_p = 10 \text{ mi/h}$
- $q_p = 1200 \text{ veh/h}$
- $K_p = 120 \text{ veh/mi}$
- $u_d = 40 \text{ mi/h}$
- $q_d = 0 \text{ veh/h}$
- $K_d = 0 \text{ veh/mi}$



Analytical Method

$$u_{sw} = \frac{q_b - q_a}{K_b - K_a} \text{ where } b \text{ is the conditions upstream of } a$$



- $u_{sw} > 0$, shockwave \rightarrow
- < 0 , shockwave \leftarrow
- $= 0$, stationary

$$\textcircled{1} \quad u_x, u_y > 0$$

$u_y > u_x$ forward

$u_y < u_x$ backward

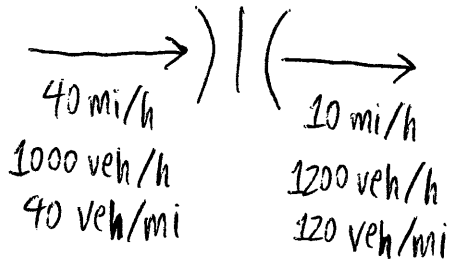
$$\textcircled{2} \quad u_x > 0, u_y < 0$$

$$\textcircled{3} \quad u_x, u_y < 0$$

similar to $\textcircled{1}$

10/8/08

Review

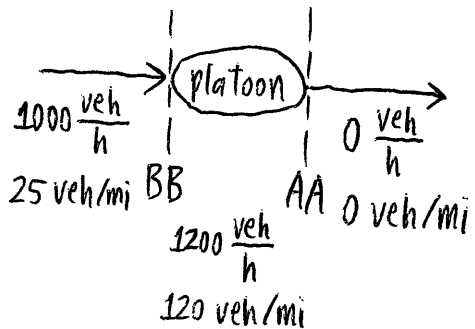


Exam 1 Fri

* 5 or 6 problems

* open book

Example 3.5

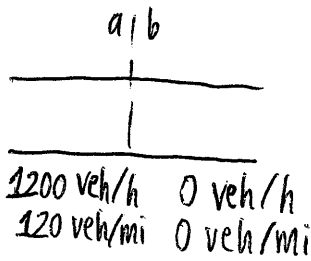


Find:

* $U_{sw, BB}$

* $U_{sw, AA}$

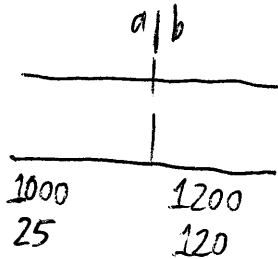
* $U_{sw, AA} - U_{sw, BB}$



$$U_{sw, AA} = \frac{q_b - q_a}{k_b - k_a}$$

$$= \frac{0 - 1200}{0 - 120}$$

$$= +10 \text{ mi/h}$$



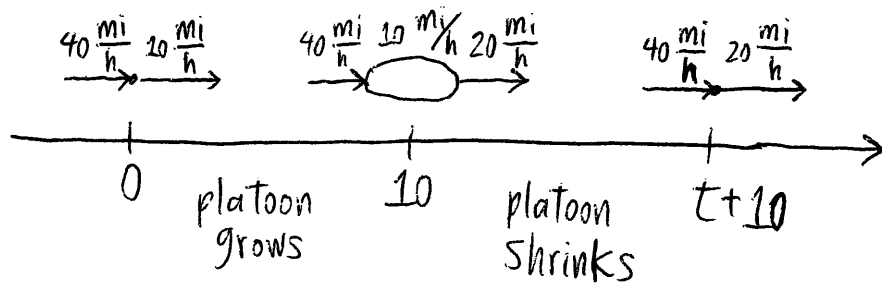
$$U_{sw, BB} = \frac{q_b - q_a}{k_b - k_a}$$

$$= \frac{1200 - 1000}{120 - 25}$$

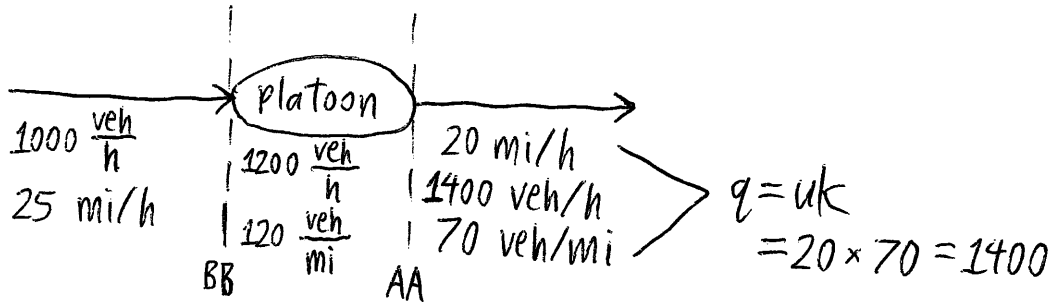
$$= +2.1 \text{ mi/h}$$

$$\Delta U_{sw} = U_{sw, AA} - U_{sw, BB}$$

$$= 10 - 2.1 = 7.9 \text{ mi/h}$$



Example 3.6



From 3.5 $\Delta u \text{ platoon} = 7.9 \text{ mi/h}$

$$l = uT = 7.9 \frac{\text{mi}}{\text{h}} \times \frac{1}{6} \text{ h} = 1.3 \text{ mi}$$

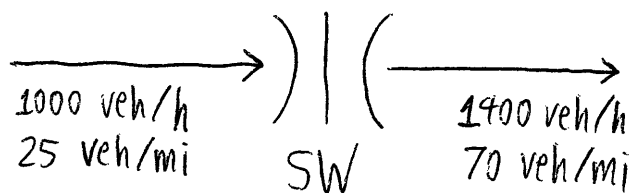
$$u_{\text{sw, BB}} = 2.1 \text{ mi/h}$$

$$u_{\text{sw, AA}} = \frac{1400 - 1200}{70 - 120} = \frac{200}{-50} = -4 \text{ mi/h}$$

$$\Delta u = -4 - 2.1 = -6.1 \text{ mi/h}$$

$$t = \frac{l}{u} = \frac{1.3 \text{ mi}}{-6.1 \text{ mi/h}} = 0.21 \text{ h} = 12 \text{ mins}$$

Example 3.7



$$u_{sw} = \frac{q_b - q_a}{k_b - k_a} = \frac{1400 - 1000}{70 - 25} = +8.9 \text{ mi/h}$$

Exercise 3.12

Test Run	Test Veh Speed (mi/h)	$M_o - M_p$ Veh
1	10	100
2	20	-150

eq 3.5.4 $\frac{M}{T} = q - kV$
where $M = M_o - M_p$

$$T_1 = 0.5 \text{ h} \quad V_1 = 10 \quad M_1 = 100$$

$$T_2 = 0.25 \text{ h} \quad V_2 = 20 \quad M_2 = -150$$

$$\frac{M_1}{T_1} = q - kV_1 \quad (1)$$

$$- \frac{M_2}{T_2} = q - kV_2 \quad (2)$$

$$\frac{M_1}{T_1} - \frac{M_2}{T_2} = (q - kV_1) - (q - kV_2)$$

$$\frac{M_1}{T_1} - \frac{M_2}{T_2} = -kV_1 + kV_2 = k(V_2 - V_1)$$

$$\frac{100}{.5} - \frac{-150}{.25} = k(20 - 10)$$

$$k = \frac{\frac{100}{.5} + \frac{150}{.25}}{20 - 10} = 80 \text{ veh/mi}$$

$$\frac{100}{.5} = q - 80(10)$$

$$q = \frac{100}{.5} + 80(10) = 1000 \frac{\text{veh}}{\text{h}}$$

$$k = 80 \text{ veh/mi}$$

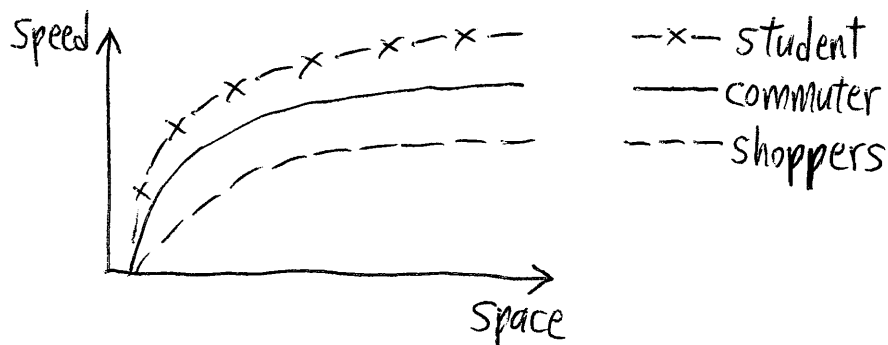
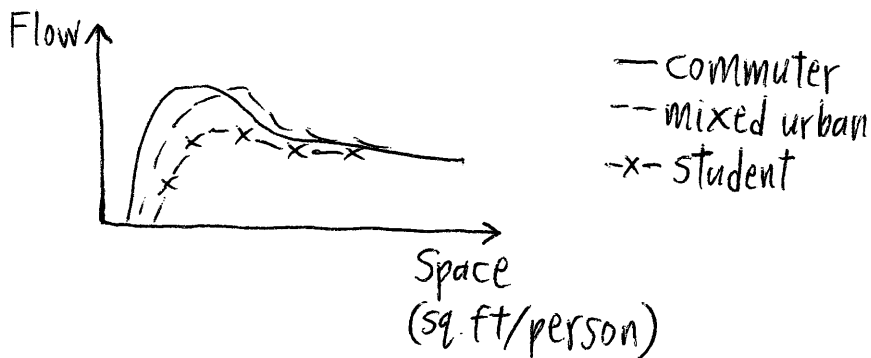
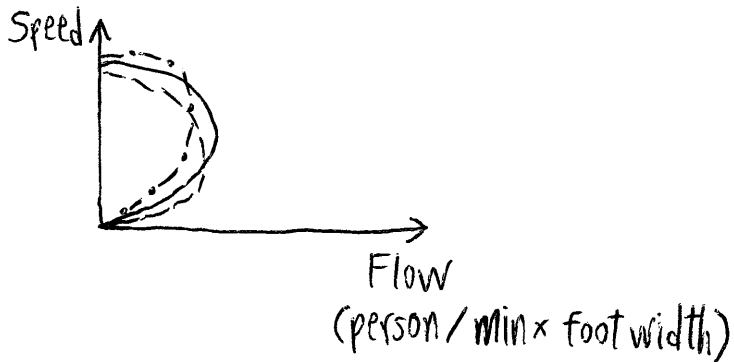
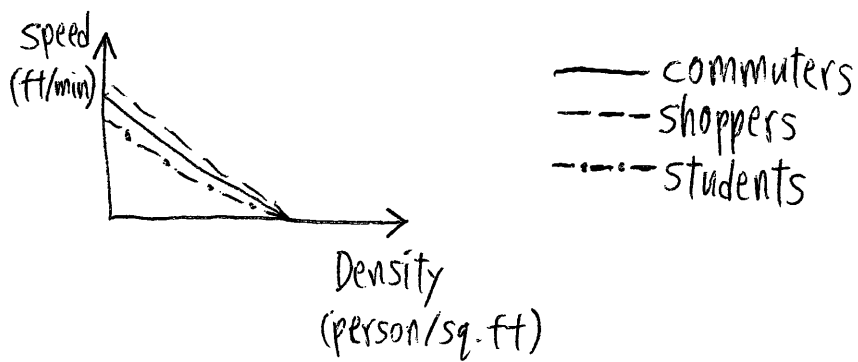
$$q = 1000 \text{ veh/h}$$

$$u = q/k = 12.5 \text{ mi/h}$$

$$S = 1/k = 0.013 \text{ mi} = 66 \text{ ft}$$

$$h = 1/q = 0.001 \text{ h} = 3.6 \text{ s}$$

10/13/08

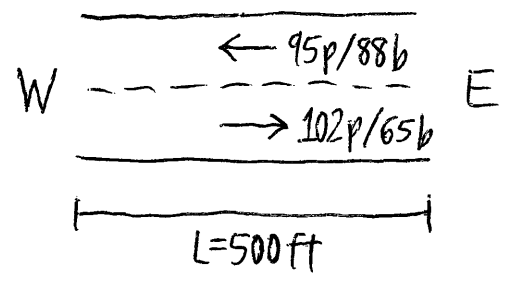


MP: number of events per hour that a bicyclist experiences

$$MP_{\text{exclusive}} = V_o + 0.118 V_s$$

$$MP_{\text{shared}} = 2.5 V_{p_o} + V_{b_o} + 3 V_{p_s} + 0.118 V_{b_s}$$

Ex.



Direction	Pedest. Vol	Biker Vol
EB	102	65
WB	95	88

Pedestrians EB

$$MP_{EB} = \frac{3600}{95} = 37.9 \text{ s} \quad \text{LOS C}$$

$$3600 \text{ s} = 1 \text{ hr}$$

Bikers EB

$$MP = V_0 + 0.118 V_s$$

$$= 88 + 0.118(65) = 95.7$$

LOS C

Ped & Bike EB

Ped

$$\frac{3600}{95+88} = 19.6 \text{ s} \quad \text{LOS D}$$

Bike

$$MP = 2.5V_{p0} + V_{b0} + 3V_{ps} + 0.118V_{bs}$$

$$= 2.5(95) + 88 + 3(102) + 0.118(65)$$

$$= 639.2$$

Pedestrians WB

$$MP_{WB} = \frac{3600}{102} = 35.3 \text{ s} \quad \text{LOS C}$$

Bikers WB

$$MP = V_0 + 0.118 V_s$$

$$= 65 + 0.118(88) = 75.4$$

LOS C

Ped & Bike WB

Ped

$$\frac{3600}{102+65} = 21.6 \text{ s} \quad \text{LOS D}$$

Bike

$$MP = 2.5V_{p0} + V_{b0} + 3V_{ps} + 0.118V_{bs}$$

$$= 2.5(102) + 65 + 3(95) + 0.118(88)$$

$$= 615.4$$

10/15/08

Transit Systems

q veh/h

$N = qT$ T_{rt} : time to complete trip (roundtrip)

$F = N \cdot \frac{T_{rt}}{T}$ $F = qT \cdot \frac{T_{rt}}{T} = qT_{rt}$ T_{rt} : sum of travel time between stops and dwelling time (time at stop)

dwelling time: $d_w = 20 - 90$ s

Ex. 10,000 passengers

2h

$T_{rt} = 30$ min

75 average occupancy

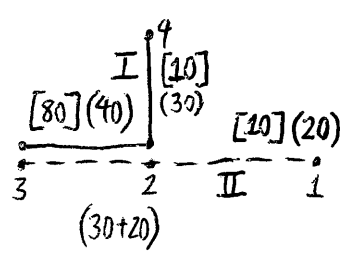
$$N = \frac{\text{\# of passengers}}{\text{capacity of veh}}$$

$$N = \frac{10000}{75} = 134 \text{ departures in 2 hrs}$$

$$q = \frac{134}{2} = 67 \text{ veh/hr}$$

$$F = \frac{67}{2} = 34 \text{ veh}$$

Ex.



[] outbound mov. w.r.t 3
() inbound mov. w.r.t 3

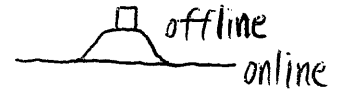
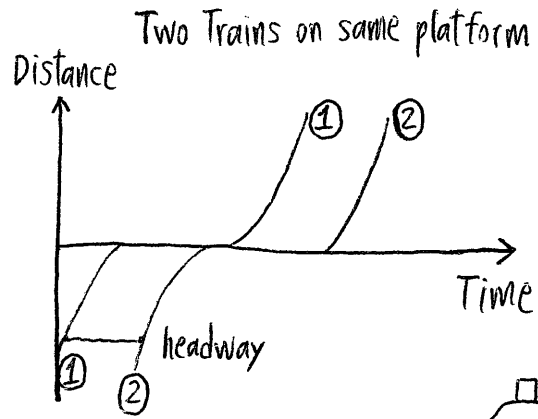
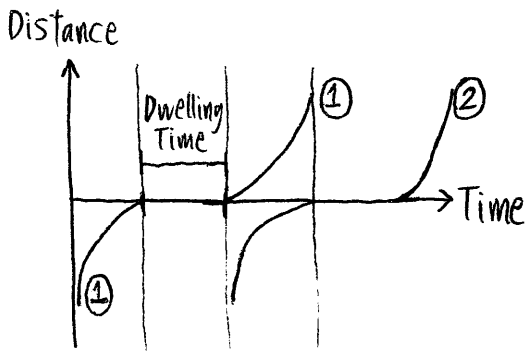
$N_I \geq 30$ departures

$N_{II} \geq 20$ departures

4-2 (I) 30 buses

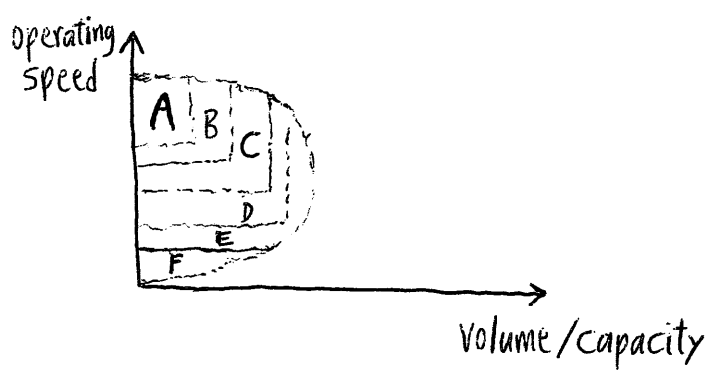
1-2 (II) 20 buses

2-3 add 30 buses



$$h_{min} = T_{dwell} + \left(\frac{2NL}{a_n}\right)^{1/2} + \delta + \frac{u}{2d_f} - \frac{u}{2d_d} + \frac{NL + x_0}{u}$$

10/17/08



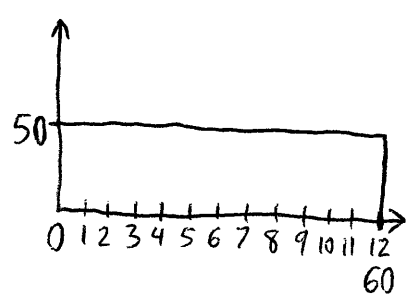
$$PHF = \frac{V}{q} = \frac{V}{N_t \left(\frac{60}{t}\right)}$$

PHF=1 uniform demand

PHF → 0 peaked demand

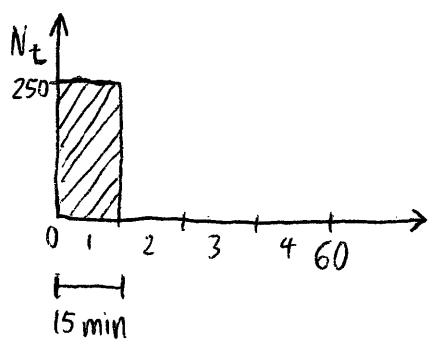
Ex. 50 vehicles
 t = 5 mins
 12 intervals

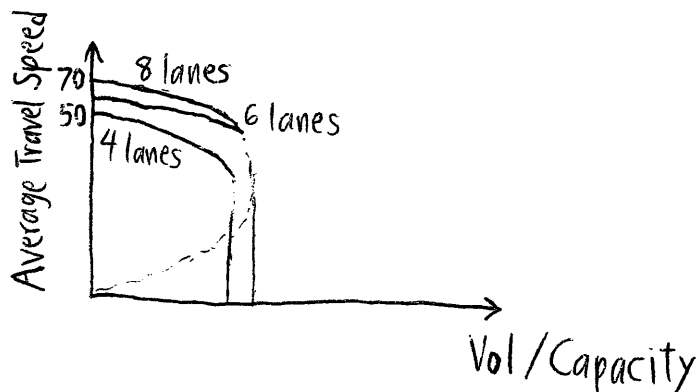
$$PHF = \frac{V}{q} = \frac{V}{N_t \left(\frac{60}{t}\right)} = \frac{600}{50 \left(\frac{60}{5}\right)} = 1$$



Ex. $N_t = 250$ veh
 t = 15 mins
 V = 250 veh

$$PHF = \frac{250}{250 \left(\frac{60}{15}\right)} = 0.25$$





- $C = 2000 \text{ veh/h}$ (70 mi/h)
- $C = 1900 \text{ Veh/h}$ (60 mi/h)
- $C = 1800 \text{ veh/h}$ (50 mi/h)

$$D = \frac{V_p}{S} = \frac{\text{flow rate (pc/h/ln)}}{\text{average passenger car speed (mi/h)}}$$

$$V_p = \frac{V}{\text{PHF} \cdot N \cdot f_{HV} \cdot f_{dp}}$$

↑
heavy vehicle

$$f_{HV} = \frac{1}{1 + P_T(E_T - 1) + P_R(E_R - 1)}$$

$$f_{dp} = 0.8 - \frac{1.00}{\text{all commuters}}$$

FFS measured under LOS A

$$FFS = BFFS - f_{LW} - f_{LC} - f_N - f_{INT}$$

↑ ↑
<60 <5

$$FFS = BFFS - 1.9(12 - W)^{1.8} - (2.4 - 0.4 \times LC) - (7.5 - 1.5 \times N) + 2.5 - 1.5 \text{ Access}$$

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Ex. $N=3$ lanes per direction

$$L=11 \text{ ft}$$

3 ft lateral distance

1 interchange per mile

$$V=3,080 \text{ veh/h}$$

$$PHF=0.88$$

$$N_T=154$$

Assume all of them
are commuters*Find E_{HV} on pg. 154

$$\begin{aligned}
 S \rightarrow FFS &= 70 - 1.9(12 - W)^{1.8} - (2.4 - 0.4LC) - (7.5 - 1.5N) + (2.5 - 1.5ACC) \\
 &= 70 - 1.9(12 - 11)^{1.8} - (2.4 - 0.4(3)) - (7.5 - 1.5(3)) + (2.5 - 1.5(1)) \\
 &= 64.9 \text{ mi/h}
 \end{aligned}$$

$$D = \frac{1195}{64.9} = 18.4 \text{ pc/h/l LOS C}$$

Table 4.5.1

$$D = \frac{V_p}{S}$$

$$\begin{aligned}
 f_{HV} &= \frac{1}{1 + P_{HV}(E_{HV} - 1)} \\
 &= \frac{1}{1 + 0.05(1.5 - 1)} = 0.976
 \end{aligned}$$

$$V_p = \frac{V}{PHF \cdot N \cdot f_{HV} \cdot f_{dp}}$$

$$= \frac{3080}{0.88 \times 3 \times 0.976 \times 1} = 1195 \text{ pc/h}$$

Ex. 12

$$5 \text{ min} = t$$

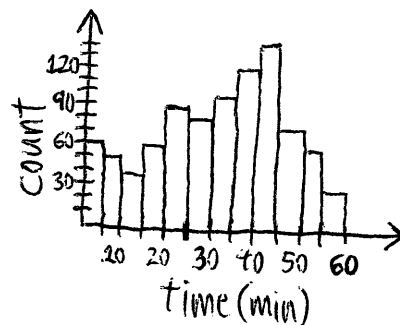
60 | 50 | 40 | 60 | 90 | 80 | 100 | 120 | 140 | 75 | 60 | 30

$$PHF = \frac{V}{N_t \left(\frac{60}{t}\right)} = \frac{925}{140 \times \left(\frac{60}{5}\right)} = 0.55$$

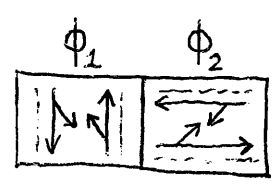
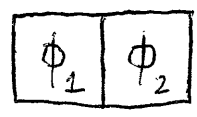
where: V = sum of observed values N_t = max of observed values

$$F_i = N_i \times \frac{60}{t}$$

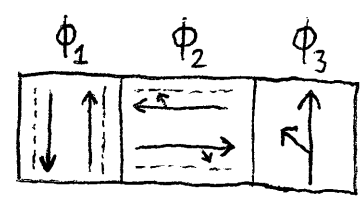
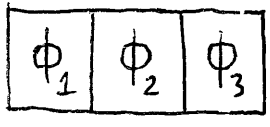
$$F_1 = 60 \times \frac{60}{5} = 720 \text{ veh/h} \quad F_{12} = 30 \times \frac{60}{5} = 360 \text{ veh/h}$$



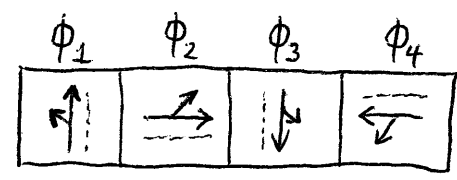
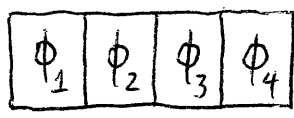
Ex.



Ex.



Ex.



10/22/08

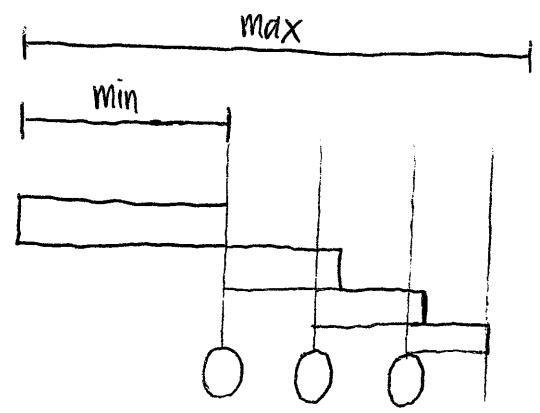
Project Topics

- LOS intersection
- Cycle Length
- Design Survey
- Mode Choice Model
- Parking
- GIS & Land Use

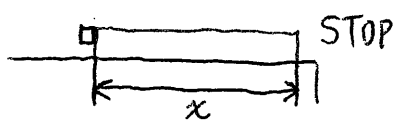
- Car Ownership
- HOT/HOV Lanes on Beltway

Cycle Length

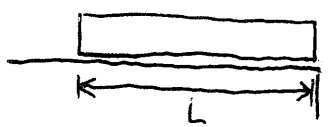
Green \rightarrow 30-60s
 $\text{min} < \text{Green} < \text{max}$



Short Loop = detects if vehicle passes



Long Loop = detects how many vehicles



$$L = 1.47V(G - V_i) - L_v$$

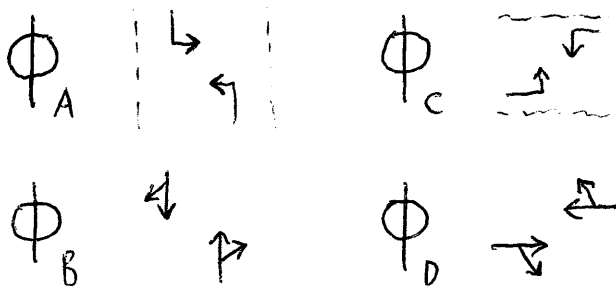
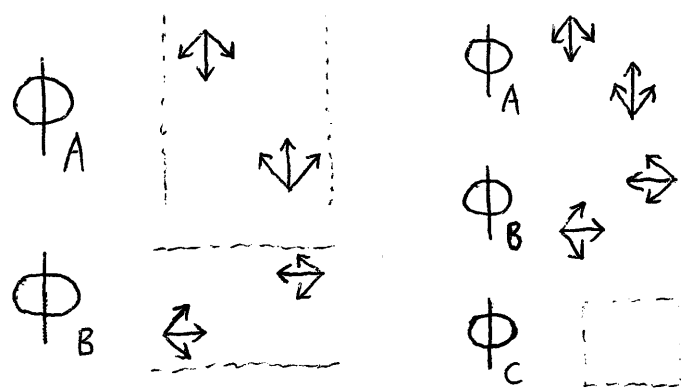
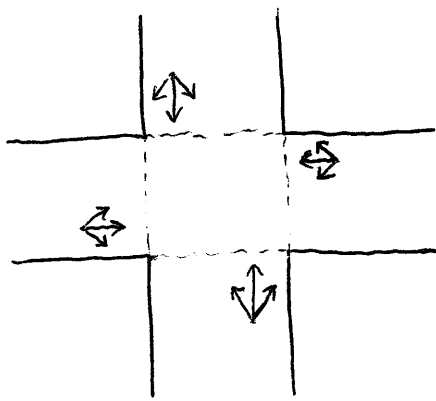
L = length of the loop
 V = approach speed mi/h

$$G = 2-5 \text{ s}$$

V_i = vehicle interval to travel distance L

L_v = vehicle length

$$\text{Minimum Green} = 4s + 2n$$

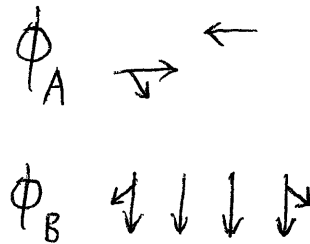
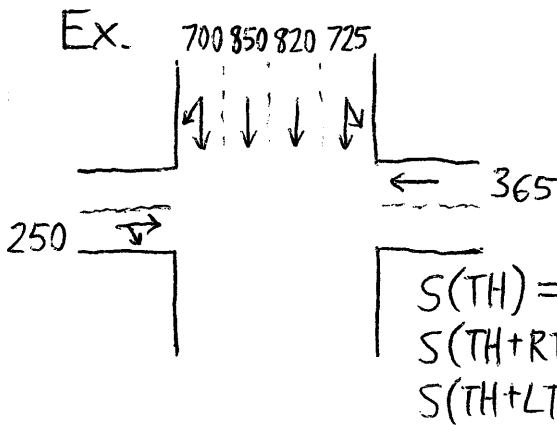


$$C_0 = \frac{1.5L + 5}{1 - CS}$$

C_0 = optimal cycle length

L = total lost time (3-4s)

CS = flow ratio of critical movement



$$\phi_A \max \left\{ \frac{365}{1800}, \frac{250}{1600} \right\} = \max \{ 0.147, 0.203 \} = 0.203$$

$$\phi_B \max \left\{ \frac{700}{1600}, \frac{850}{1800}, \frac{820}{1800}, \frac{725}{1700} \right\} = 0.464$$

$$CS = 0.464 + 0.203 = 0.667$$

$$L = 4s \times 2 = 8s$$

$$C_0 = \frac{1.5L + 5}{1 - CS} = \frac{1.5(8) + 5}{1 - 0.667} = 51s \begin{matrix} < 35s \\ < 65s \end{matrix}$$